

Ch10. Basic Regression Analysis with Time Series Data

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The Nature of Time Series Data

The Nature of Time Series Data

- A times series is a temporal ordering of observations; it may not be arbitrarily reordered.
- **Typical Features**: serial correlation/nonindependence of observations.
- How should we think about the randomness in time series data?
 - The outcome of economic variables (e.g., GDP, Dow Jones) is uncertain; they should therefore be modeled as random variables.
 - Time series are sequences of r.v.'s (= **stochastic process/time series process**).
 - Randomness does not come from sampling from a population as the cross-sectional data.
 - "Sample" = the one realized path of the time series out of the many possible paths the stochastic process could have taken. [[figure here](#)]

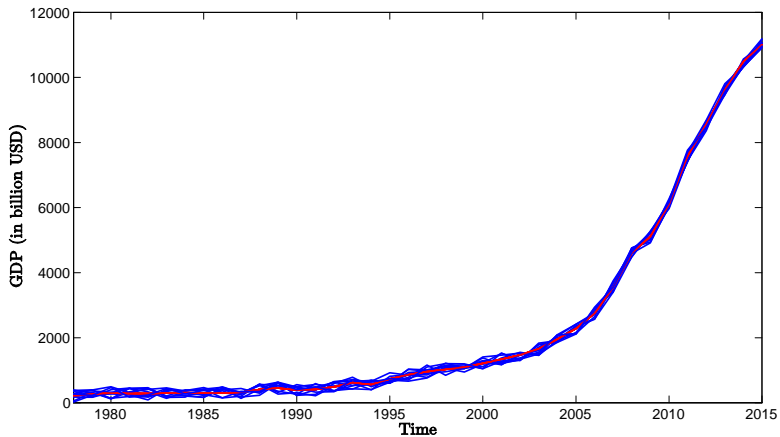


Figure: China GDP from 1978 to 2015: Red is the **Realized** GDP and Blues are **Potential** GDPs

Example: US Inflation and Unemployment Rates 1948-2003

TABLE 10.1 Partial Listing of Data on U.S. Inflation and Unemployment Rates, 1948–2003

Year	Inflation	Unemployment
1948	8.1	3.8
1949	-1.2	5.9
1950	1.3	5.3
1951	7.9	3.3
.	.	.
.	.	.
.	.	.
1998	1.6	4.5
1999	2.2	4.2
2000	3.4	4.0
2001	2.8	4.7
2002	1.6	5.8
2003	2.3	6.0

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- Here, there are only two time series. There may be many more variables whose paths over time are observed simultaneously.
- Time series analysis focuses on modeling the dependency of a variable on its own past, and on the present and past values of other variables.

Autocorrelation

- The correlation of a series with its own lagged values is called **autocorrelation** or **serial correlation**.
- The first autocorrelation of y_t is $\text{Corr}(y_t, y_{t-1})$ and the first autocovariance of y_t is $\text{Cov}(y_t, y_{t-1})$. Thus

$$\text{Corr}(y_t, y_{t-1}) = \frac{\text{Cov}(y_t, y_{t-1})}{\sqrt{\text{Var}(y_t) \text{Var}(y_{t-1})}} = \rho_1.$$

- Similarly, the j th autocorrelation is

$$\text{Corr}(y_t, y_{t-j}) = \frac{\text{Cov}(y_t, y_{t-j})}{\sqrt{\text{Var}(y_t) \text{Var}(y_{t-j})}} = \rho_j.$$

- These are population correlations - they describe the population joint distribution of (y_t, y_{t-1}) and (y_t, y_{t-j}) .
- The j th **sample autocorrelation** is an estimate of the j th population autocorrelation, i.e., the sample analog of $\text{Corr}(y_t, y_{t-j})$.

Sample Autocorrelation

- Recall that for a sample $\{(x_i, y_i) : i = 1, \dots, n\}$,

$$\widehat{\text{Cov}}(x, y) = \frac{1}{n} \sum_{i=1}^n (x_i - \bar{x})(y_i - \bar{y}).$$

- For a time series $\{y_t : t = 1, \dots, T\}$, $\widehat{\text{Cov}}(y_t, y_{t-j})$ is supposedly

$$\widehat{\text{Cov}}(y_t, y_{t-j}) = \frac{1}{T} \sum_{t=1}^T (y_t - \bar{y}_t)(y_{t-j} - \bar{y}_{t-j}).$$

- However,

$$\underbrace{y_1, \dots, y_{j-1}, y_j, y_{j+1}, \dots, y_{T-j-1}, y_{T-j}, y_{T-j+1}, \dots, y_T}_{y_{t-j}}$$

and

$$y_1, \dots, y_{j-1}, y_j, \overbrace{y_{j+1}, \dots, y_{T-j-1}, y_{T-j}, y_{T-j+1}, \dots, y_T}^{y_t},$$

the summation should be from $j+1$ to T ; otherwise, y_{t-j} for $t \leq j$ is not defined.

continue

- Correspondingly,

$$\bar{y}_t = \bar{y}_{j+1,T} \equiv \frac{1}{T-j} \sum_{t=j+1}^T y_t,$$

$$\overline{y_{t-j}} = \bar{y}_{1,T-j} \equiv \frac{1}{T-j} \sum_{t=1}^{T-j} y_t.$$

- As a result, the j th sample autocorrelation is

$$\hat{\rho}_j = \frac{\widehat{\text{Cov}}(y_t, y_{t-j})}{\widehat{\text{Var}}(y_t)},$$

where

$$\widehat{\text{Cov}}(y_t, y_{t-j}) = \frac{1}{T-j} \sum_{t=j+1}^T (y_t - \bar{y}_{j+1,T}) (y_{t-j} - \bar{y}_{1,T-j}),$$

$$\widehat{\text{Var}}(y_t) = \frac{1}{T} \sum_{t=1}^T (y_t - \bar{y}_{1,T})^2.$$

- Note:** Here, we assume constant variance, i.e., $\text{Var}(y_t)$ does not depend on t .

Example: US CPI Inflation Rate

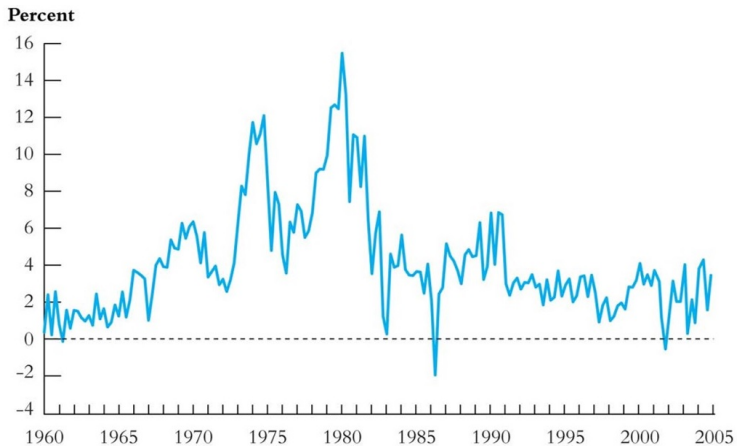


Figure: US Quarterly CPI Inflation Rate: 1960:I-2004:IV

Sample Autocorrelations of Inf_t and ΔInf_t

- The sample autocorrelations of the quarterly rate of U.S. inflation (Inf_t) and the quarter-to-quarter change in the quarterly rate of inflation ($\Delta Inf_t \equiv Inf_t - Inf_{t-1}$) are summarized in the following table:

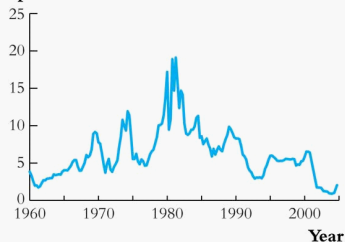
Lag	Inf_t	ΔInf_t
1	0.84	-0.26
2	0.76	-0.25
3	0.76	0.29
4	0.67	-0.06

Table: First Four Sample Autocorrelations of the US Inflation Rate and Its Change

- The inflation rate is highly serially correlated ($\hat{\rho}_1^{Inf} = 0.84$).
- Last quarter's inflation rate contains much information about this quarter's inflation rate.
- What's the intuitive meaning of $\hat{\rho}_1^{\Delta Inf} = -0.26 < 0$?
- the plot is also dominated by multiyear swings.

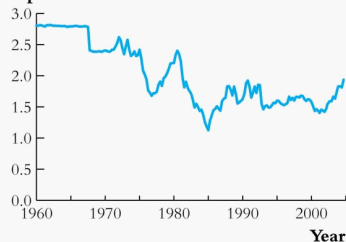
Other Economic Time Series

Percent per Annum



(a) Federal Funds Interest Rate

Dollars per Pound



(b) U.S. Dollar/British Pound Exchange Rate

History of Cointegration

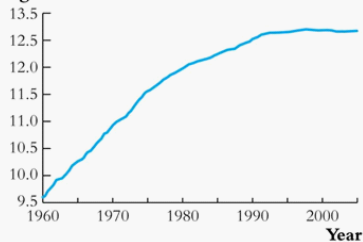
- Engle, R.F. and C.W.J. Granger, 1987, Co-integration and Error Correction: Representation, Estimation and Testing, *Econometrica*, 55, 251–276.



Clive Granger (1934-2009),
UCSD, 2003NP, 1959NottinghamPhD

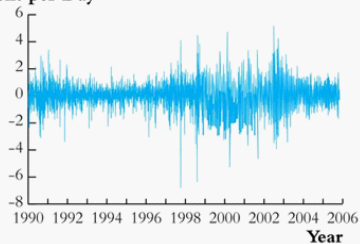
continue

Logarithm



(c) Logarithm of GDP in Japan

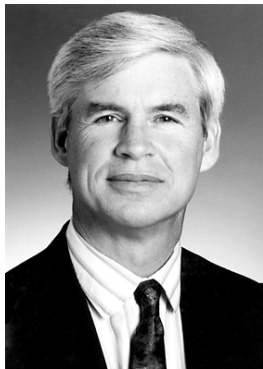
Percent per Day



(d) Percentage Changes in Daily Values of the NYSE Composite Stock Index

History of Autoregressive Conditional Heteroskedasticity (ARCH)

- Engle, R.F., 1982, Autoregressive Conditional Heteroscedasticity with Estimates of Variance of United Kingdom Inflation, *Econometrica*, 50, 987-1008.



Robert Engle (1942-),
NYU, 2003NP, 1969CornellPhD

Examples of Time Series Regression Models

a: Static Models

- A **static model** relating y to z is

$$y_t = \beta_0 + \beta_1 z_t + u_t.$$

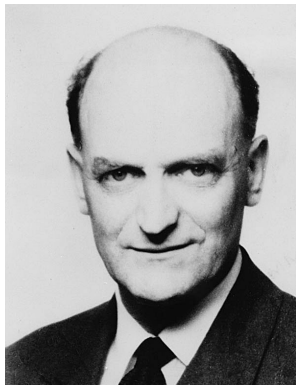
- In static time series models, the current value of one variable is modeled as the result of the current values of explanatory variables.
- **Example** (**Phillips Curve** [\[photo here\]](#)): There is a contemporaneous relationship between unemployment and inflation [\[figure here\]](#),

$$inf_t = \beta_0 + \beta_1 unem_t + u_t.$$

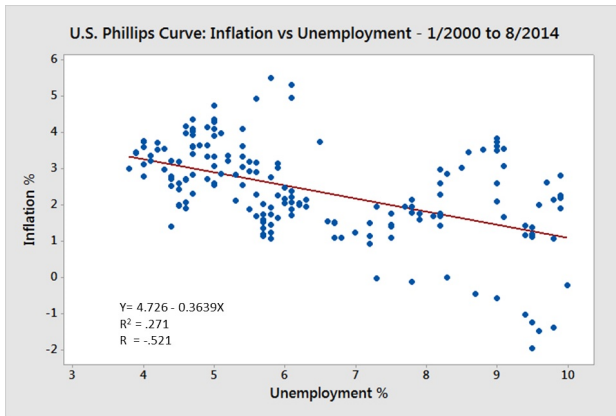
- **Example**: The current murder rate is determined by the current conviction rate, unemployment rate, and fraction of young males in the population,

$$mrd rte_t = \beta_0 + \beta_1 convrte_t + \beta_2 unem_t + \beta_3 yngmle_t + u_t.$$

History of The Phillips Curve



A.W. Phillips (1914-1975),
New Zealander, LSE, 1949 LSE Sociology PhD



Source Data: FRED Database
Inflation: CPI for All Urban Consumers

b: Finite Distributed Lag Models

- In **finite distributed lag (FDL) models**, the explanatory variables are allowed to influence the dependent variable with a time lag.
- Mathematically,

$$y_t = \alpha_0 + \delta_0 z_t + \delta_1 z_{t-1} + \cdots + \delta_q z_{t-q} + u_t$$

is an FDL of order q , where q is finite.

- **Example:** The fertility rate may depend on the tax value of a child, but for biological and behavioral reasons, the effect may have a lag,

$$gft_t = \alpha_0 + \delta_0 pe_t + \delta_1 pe_{t-1} + \delta_2 pe_{t-2} + u_t,$$

where

gft_t = general fertility rate (children born per 1,000 women in year t)

pe_t = tax exemption in year t

Effect of a Transitory Shock

- If there is a one time shock in a past period, the dependent variable will change temporarily by the amount indicated by the coefficient of the corresponding lag.
- Consider an FDL of order 2,

$$y_t = \alpha_0 + \delta_0 z_t + \delta_1 z_{t-1} + \delta_2 z_{t-2} + u_t.$$

- At time t , z increases by one unit from c to $c + 1$ and then reverts to its previous level at time $t + 1$:

$$\dots, z_{t-2} = c, z_{t-1} = c, z_t = c + 1, z_{t+1} = c, z_{t+2} = c, \dots$$

- Then, by setting the errors to be zero,

$$y_{t-1} = \alpha_0 + \delta_0 c + \delta_1 c + \delta_2 c,$$

$$y_t = \alpha_0 + \delta_0 (c + 1) + \delta_1 c + \delta_2 c,$$

$$y_{t+1} = \alpha_0 + \delta_0 c + \delta_1 (c + 1) + \delta_2 c,$$

$$y_{t+2} = \alpha_0 + \delta_0 c + \delta_1 c + \delta_2 (c + 1),$$

$$y_{t+3} = \alpha_0 + \delta_0 c + \delta_1 c + \delta_2 c.$$

continue

- So

$$y_t - y_{t-1} = \delta_0,$$

i.e., δ_0 is the immediate change in y due to the one-unit increase in z at time t , and is usually called **impact propensity** or **impact multiplier**.

- Similarly,

$$\delta_1 = y_{t+1} - y_{t-1}$$

is the change in y one period after the temporary change, and

$$\delta_2 = y_{t+2} - y_{t-1}$$

is the change in y two periods after the temporary change.

- At time $t + 3$, y has reverted back to its initial level: $y_{t+3} = y_{t-1}$ because only two lags of z appears in the FDL model.
- In summary,

$$\delta_j = \frac{\partial y_{t+j}}{\partial z_t}.$$

- **Lag Distribution:** δ_j as a function of j , which summarizes the dynamic effect that a temporary increase in z has on y . [\[figure here\]](#)

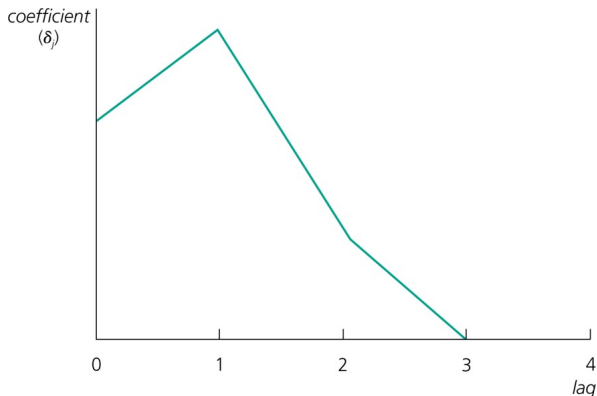


Figure: A Lag Distribution with Two Nonzero Lags

- The effect is biggest after a lag of one period. After that, the effect vanishes (if the initial shock was transitory).

Effect of Permanent Shock

- If there is a permanent shock in a past period, i.e., the explanatory variable permanently increases by one unit, the effect on the dependent variable will be the cumulated effect of all relevant lags. This is a long-run effect on the dependent variable.
- At time t , z permanently increases by one unit from c to $c + 1$:

$$z_s = c, s < t \text{ and } z_s = c + 1, s \geq t.$$

- Then,

$$y_{t-1} = \alpha_0 + \delta_0 c + \delta_1 c + \delta_2 c,$$

$$y_t = \alpha_0 + \delta_0 (c + 1) + \delta_1 c + \delta_2 c,$$

$$y_{t+1} = \alpha_0 + \delta_0 (c + 1) + \delta_1 (c + 1) + \delta_2 c,$$

$$y_{t+2} = \alpha_0 + \delta_0 (c + 1) + \delta_1 (c + 1) + \delta_2 (c + 1),$$

$$y_{t+3} = y_{t+2}.$$

continue

- With a permanent increase in z , after one period, y will increase by $\delta_0 + \delta_1$, and after two periods, y will increase by $\delta_0 + \delta_1 + \delta_2$ and then stay there.
- The sum of the coefficients on current and lagged z , $\delta_0 + \delta_1 + \delta_2$, is the long-run change in y given a permanent increase in z , and is called the **long-run propensity (LRP)** or **long-run multiplier**.
- In summary, in an FDL of order q ,

$$LRP = \delta_0 + \delta_1 + \dots + \delta_q = \frac{\partial y_{t+q}}{\partial z_t} + \dots + \frac{\partial y_{t+q}}{\partial z_{t+q}}.$$

- In the figure, the long run effect of a permanent shock is the cumulated effect of all relevant lagged effects. It does not vanish (if the initial shock is a permanent one).

(**) Finite Sample Properties of OLS under Classical Assumptions

Standard Assumptions for the Time Series Model

- **Assumption TS.1** (Linear in Parameters):

$$y_t = \beta_0 + \beta_1 x_{t1} + \cdots + \beta_k x_{tk} + u_t.$$

- The time series involved obey a linear relationship.
 - The stochastic processes $y_t, x_{t1}, \dots, x_{tk}$ are observed, the error process u_t is unobserved.
 - The definition of the explanatory variables is general, e.g., they may be lags or functions of other explanatory variables.
- **Assumption TS.2** (No Perfect Collinearity): In the sample (and therefore in the underlying time series process), no independent variable is constant nor a perfect linear combination of the others.

continue

- Assumption TS.3 (Zero Conditional Mean):

$$E[u_t | \mathbf{X}] = 0,$$

where

$$\mathbf{X} = \begin{pmatrix} x_{11} & x_{12} & \cdots & x_{1k} \\ \vdots & \vdots & \vdots & \vdots \\ x_{t1} & x_{t2} & \cdots & x_{tk} \\ \vdots & \vdots & \vdots & \vdots \\ x_{T1} & x_{T2} & \cdots & x_{Tk} \end{pmatrix}$$

collects all the information on the complete time paths of all explanatory variables.

- Assumption TS.3 assumes that the mean value of the unobserved factors is unrelated to the values of the explanatory variables in all periods:

$$\text{Cov}(u_t, x_{sj}) = 0 \text{ for } \underline{\text{all } j} \text{ and } \underline{\text{all } t} \text{ and } \underline{s}.$$

- Assumption TS.3 is the **strict exogeneity** assumption for the regressors,

Discussion of Assumption TS.3

- Contemporaneous Exogeneity:

$$E[u_t | \mathbf{x}_t] = 0,$$

where $\mathbf{x}_t = (x_{t1}, \dots, x_{tk})$ is the values of all explanatory variables in period t .

- It implies $Cov(u_t, x_{tj}) = 0$ for all j .

- So strict exogeneity is stronger than contemporaneous exogeneity. In the cross-sectional case, they are equivalent due to random sampling.
- TS.3 rules out feedback from the dependent variable on future values of the explanatory variables; this is often questionable especially if explanatory variables "adjust" to past changes in the dependent variable, e.g., $x_t = y_{t-1}$, then $Cov(u_{t-1}, x_t) = Cov(u_{t-1}, y_{t-1}) \neq 0$.
- Example:** In a simple static model to explain a city's murder rate in terms of police officers per capita,

$$mrd rte_t = \beta_0 + \beta_1 polpc_t + u_t,$$

if $Cov(polpc_{t+1}, u_t) \neq 0$ then TS.3 fails even if $Cov(u_t, polpc_{t-j}) = 0$ for $j = 0, 1, 2, \dots$

- Example:** In an agricultural production function, the rainfall is strictly exogenous, while the labor input is not.
- If the error term is related to past values of the explanatory variables, one should include these values as contemporaneous regressors, i.e., use the FDL model.

a: Unbiasedness of OLS

- **Theorem 10.1:** Under assumptions TS.1-TS.3,

$$E \left[\widehat{\beta}_j \mid \mathbf{X} \right] = \beta_j, j = 0, 1, \dots, k,$$

for any values of β_j .

- The proof is similar to that of Theorem 3.1.
- The analysis of omitted variables bias is also similar.
- As in Chapter 3, we condition on the regressors \mathbf{X} . Conditional unbiasedness implies unconditional unbiasedness:

$$E \left[\widehat{\beta}_j \right] = E \left[E \left[\widehat{\beta}_j \mid \mathbf{X} \right] \right] = E \left[\beta_j \right] = \beta_j.$$

- **(*) Law of Iterated Expectations (LIE):** For two r.v.'s, $E[E[Y|X]] = E[Y]$.
 - **Intuition:** $E[Y|X] = \mu(X)$ averages over Y for each group of individuals with a specific X value, and then $E[E[Y|X]] = E[\mu(X)]$ averages over X by the probability of each X group, which results in the unconditional mean of Y . [\[figure here\]](#)
 - $E[u|x] = 0$ implies the unconditional mean of u , $E[u] \stackrel{LIE}{=} E[E[u|x]] = E[0] = 0$. We can also show, by applying the LIE, that $\text{Var}(u|x) = \sigma^2$ implies $\text{Var}(u) = \sigma^2$, and $E[u|x] = 0$ implies $\text{Cov}(x, u) = 0$.

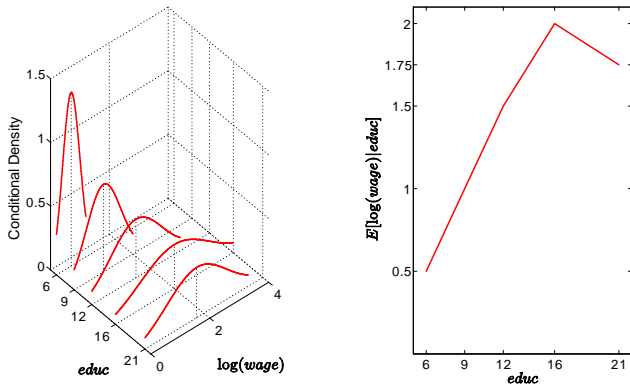


Figure: Illustration of the LIE: the distribution of $\log(\text{wage})$ given educ mimics the real data in Chapter 8

- $E[\log(\text{wage})] = E[E[\log(\text{wage}) | \text{educ}]] = E[m(\text{educ})] = \sum_{j=1}^J m(\text{educ}_j) p_j.$

Standard Assumptions for the Time Series Model (continue)

- **Assumption TS.4** (Homoskedasticity): $Var(u_t|\mathbf{X}) = Var(u_t) = \sigma^2$.
 - The volatility of the errors must not be related to the explanatory variables in any of the periods.
- A sufficient condition is that u_t is independent of \mathbf{X} and that $Var(u_t)$ is constant over time.
- In the time series context, homoskedasticity may also be easily violated, e.g., if the volatility of the dependent variable depends on regime changes (recall the Chow-test, see also the example below).
- **Assumption TS.5** (No Serial Correlation): $Cov(u_t, u_s|\mathbf{X}) = 0, t \neq s$.
 - Conditional on the explanatory variables, the unobserved factors must not be correlated over time.
- This assumption is specific to time series. In the cross-sectional case, it automatically holds due to random sampling.
- The assumption may also serve as substitute for the random sampling assumption if sampling a cross-section is not done completely randomly.
- In this case, given the values of the explanatory variables, errors have to be uncorrelated across cross-sectional units (e.g., states).

More on Assumption TS.5

- This assumption may easily be violated if, conditional on knowing the values of the independent variables, omitted factors are correlated over time.
- Strictly, suppose the true model is

$$y_t = \beta_0 + \beta_1 x_t + \beta_2 z_t + u_t,$$

while we fit

$$y_t = \beta_0 + \beta_1 x_t + v_t.$$

- If $\text{Cov}(z_t, z_s) \neq 0$, $t \neq s$, then

$$\text{Cov}(v_t, v_s) = \text{Cov}(\beta_2 z_t + u_t, \beta_2 z_s + u_s) = \beta_2^2 \text{Cov}(z_t, z_s)$$

even if

$$\text{Cov}(z_t, u_s) = 0 \text{ for all } t, s \text{ and } \text{Cov}(u_t, u_s) = 0 \text{ for } t \neq s.$$

b: Three Parallel Theorems

- **Theorem 10.2** (OLS Sampling Variances): Under assumptions TS.1-TS.5,

$$\text{Var}(\hat{\beta}_j | \mathbf{X}) = \frac{\sigma^2}{\text{SST}_j(1 - R_j^2)}, j = 1, \dots, k.$$

- **Theorem 10.3** (Unbiased Estimation of σ^2): Under assumptions TS.1-TS.5,

$$E[\hat{\sigma}^2] = \sigma^2,$$

where $\hat{\sigma}^2 = \frac{\text{SSR}}{T-k-1}$.

- **Theorem 10.4** (The Gauss-Markov Theorem): Under assumptions TS.1-TS.5, the OLS estimators are BLUEs conditional (or unconditional) on \mathbf{X} .
- Assumptions TS.1-TS.5 are the appropriate Gauss-Markov assumptions for time series applications.

c: Inference under the Classical Linear Model Assumptions

- **Assumption TS.6** (Normality): u_t is independent of \mathbf{X} , and $u_t \stackrel{iid}{\sim} N(0, \sigma^2)$.
- This assumption implies TS.3-TS.5.
- **Theorem 10.5** (Normal Sampling Distributions): Under assumptions TS.1-TS.6, the OLS estimators have the usual normal distribution (conditional on \mathbf{X}). The usual F - and t -tests are valid. The usual construction of CIs is also valid.
- **Example** (Static Phillips Curve): The fitted regression line is

$$\widehat{inf}_t = 1.42 + .468unem_t$$

$$(1.72)(.289)$$

$$n = 49, R^2 = .053, \bar{R}^2 = .033$$

- Contrary to theory, the estimated Phillips Curve does not suggest a tradeoff between inflation and unemployment.

Discussion of CLM Assumptions

- **TS.1:** $\ln f_t = \beta_0 + \beta_1 \text{unem}_t + u_t$. The error term contains factors such as monetary shocks, income/demand shocks, oil price shocks, supply shocks, or exchange rate shocks.
- **TS.2:** A linear relationship might be restrictive, but it should be a good approximation. Perfect collinearity is not a problem as long as unemployment varies over time.
- **TS.3:** $E[u_t | \text{unem}_1, \dots, \text{unem}_T] = 0$ is easily violated. $\text{unem}_{t-1} \uparrow \implies u_t \downarrow$: past unemployment shocks may lead to future demand shocks which may dampen inflation. $u_{t-1} \uparrow \implies \text{unem}_t \uparrow$: an oil price shock means more inflation and may lead to future increases in unemployment.
- **TS.4:** $\text{Var}(u_t | \text{unem}_1, \dots, \text{unem}_T) = \sigma^2$ is violated if monetary policy is more "nervous" in times of high unemployment.
- **TS.5:** $\text{Corr}(u_t, u_s | \text{unem}_1, \dots, \text{unem}_T) = 0$ is violated if exchange rate influences persist over time (they cannot be explained by unemployment).
- **TS.6:** If TS.3-5 is questionable, TS.6 is also questionable. Also, normality is questionable.

Functional Form and Dummy Variables

Functional Form and Dummy Variables

- Logarithmic transformation has the usual elasticity interpretation. For example, in the FDL model, we can define **short-run elasticity** (corresponding to impact propensity) and **long-run elasticity** (corresponding to LRP) by using logarithmic functional forms.
- Dummy variables are often used to isolate certain periods that may be systematically different from other periods.
- **Example** (Effects of Personal Exemption on Fertility Rates): The fitted regression line is

$$\widehat{gfr}_t = 98.68 + .083pe_t - 24.24ww2_t - 31.59pill_t$$

$$(3.68) \quad (.030) \quad (7.46) \quad (4.08)$$

$$n = 72, R^2 = .473, \bar{R}^2 = .450$$

where

$ww2$ = dummy for World War II years (1941-45)

$pill$ = dummy for availability of contraceptive pill (1963-present)

- During World War II, the fertility rate was temporarily (much) lower (gfr ranges from 65 to 127 during 1913-1984).
- It has been permanently lower since the introduction of the pill in 1963.
- The effect of tax exemption is significant both statistically and economically (\$12 tax exemption \implies one more baby per 1,000 women).

Trends and Seasonality

a: Characterizing Trending Time Series

- Modelling a Linear Time Trend:

$$y_t = \alpha_0 + \alpha_1 t + e_t.$$

- $E[y_t] = \alpha_0 + \alpha_1 t$, the expected value of the dependent variable is a linear function of time. [\[figure here\]](#)
- This is equivalent to say that

$$E[\Delta y_t] = E[y_t - y_{t-1}] = \alpha_0 + \alpha_1 t - (\alpha_0 + \alpha_1 (t-1)) = \alpha_1.$$

- Modelling an Exponential Time Trend:

$$\log(y_t) = \alpha_0 + \alpha_1 t + e_t.$$

- $\frac{\partial \log(y_t)}{\partial t} = \frac{\partial y_t / y_t}{\partial t} = \alpha_1$, so the growth rate is constant over time. [\[figure here\]](#)
- This is equivalent to say that

$$E[\Delta \log(y_t)] = E[\log(y_t) - \log(y_{t-1})] = \alpha_0 + \alpha_1 t - (\alpha_0 + \alpha_1 (t-1)) = \alpha_1.$$

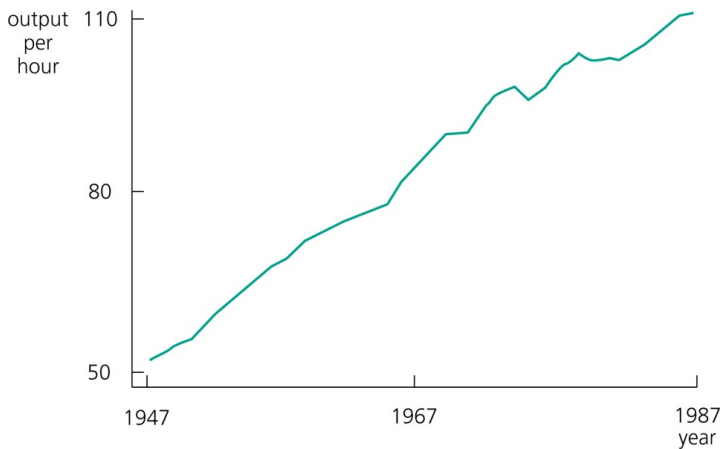


Figure: Example for a Time Series with a Linear Upward Trend

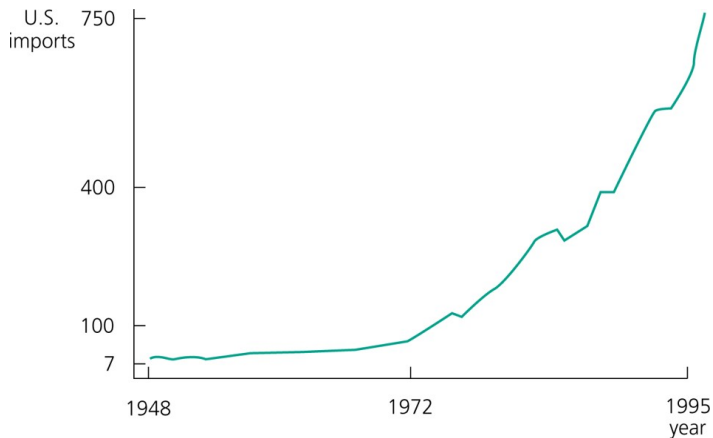


Figure: Example for a Time Series with an Exponential Trend

b: Using Trending Variables in Regression Analysis

- If trending variables are regressed on each other, a spurious relationship may arise if the variables are driven by a common trend. This is an example of **spurious regression problem**.
- In this case, it is important to include a trend in the regression:

$$y_t = \beta_0 + \beta_1 x_t + \beta_3 t + u_t.$$

- If x_t also includes a trend, then x_t is correlated with t . The regression

$$y_t = \beta_0 + \beta_1 x_t + u_t \tag{1}$$

would have an omitted variable bias. This is why the spurious regression problem appears.

- If x_t has a trend but y_t does not, then $\hat{\beta}_1$ in (1) tends to be insignificant. This is because the trending in x_t might be too dominating and obscure any partial effect it might have on y_t .
- Either y_t or some of the regressors has a time trend, add t in.

Example: Housing Investment and Prices (spurious regression)

- The fitted regression line is

$$\begin{aligned}\widehat{\log(invpc)} &= -.550 + 1.241 \log(price) \\ &\quad (.043) \quad (.382) \\ n &= 42, R^2 = .208, \bar{R}^2 = .189\end{aligned}$$

where

invpc = per capita housing investment (in thousands of dollars)

price = housing price index (equal to 1 in 1982)

- It looks as if investment and prices are positively related.
- If adding the time trend in,

$$\begin{aligned}\widehat{\log(invpc)} &= -.913 - .381 \log(price) + .0098t \\ &\quad (.136) \quad (.679) \quad (.0035) \\ n &= 42, R^2 = .341 (> .208), \bar{R}^2 = .307\end{aligned}$$

- There is no significant relationship between price and investment anymore.

c: A Detrending Interpretation of Regressions with a Time Trend

- It turns out that the OLS coefficients in a regression including a trend are the same as the coefficients in a regression without a trend but where all the variables have been **detrended** before the regression.
- This follows from the FWL theorem.
- Specifically, suppose $y \sim 1, x, t$, and we are interested in $\hat{\beta}_1$.
 - 1 $x_t \sim 1, t \implies \check{x}_t$
 - 2 $y_t \sim 1, t \implies \check{y}_t$
 - 3 $\check{y}_t \sim \check{x}_t \implies \hat{\beta}_1$

d: Computing R -Squared when the Dependent Variable Is Trending

- Due to the trend, the variance of the dependent variable will be overstated.
- It is better to first detrend the dependent variable and then run the regression on all the independent variables (plus a trend if they are trending as well).
- Specifically,
 - 1 $y_t \sim 1, t \implies \ddot{y}_t$
 - 2 $\ddot{y}_t \sim 1, x_t, t$
- The R -squared of the second-step regression is a more adequate measure of fit:

$$R^2 = 1 - \frac{SSR}{\sum_{t=1}^T \ddot{y}_t^2},$$

where $\frac{1}{T} \sum_{t=1}^T \ddot{y}_t = 0$, and

$$\bar{R}^2 = 1 - \frac{SSR / (T - 3)}{\left(\sum_{t=1}^T \ddot{y}_t^2 \right) / (T - 2)}.$$

continue

- Recall that

$$\bar{R}^2 = 1 - \frac{\hat{\sigma}_u^2}{\hat{\sigma}_y^2}.$$

- Although $\hat{\sigma}_u^2 = \frac{1}{T-k-1} \sum_{t=1}^T \hat{u}_t^2$ is unbiased to σ_u^2 , $\hat{\sigma}_y^2 = \frac{1}{T-1} \sum_{t=1}^T (y_t - \bar{y})^2$ is **not** an unbiased estimator of σ_y^2 if y_t has a trend [figure here], where \hat{u}_t is from

$$y_t \sim 1, x_t, t,$$

which is the same as the residual from $\check{y}_t \sim 1, x_t, t$.

- Note that

$$\left(\sum_{t=1}^T \check{y}_t^2 \right) \leq \sum_{t=1}^T (y_t - \bar{y})^2,$$

so

$$1 - \frac{SSR}{\sum_{t=1}^T \check{y}_t^2} \leq 1 - \frac{SSR}{\sum_{t=1}^T (y_t - \bar{y})^2},$$

i.e., the R^2 tends to be larger if y_t has not been detrended before calculating R^2 .

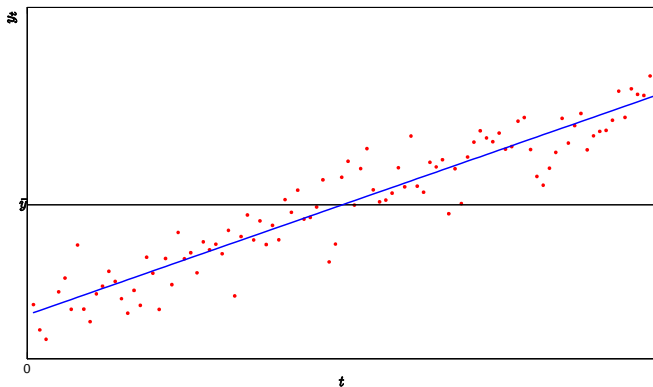


Figure: $\hat{\sigma}_y^2 = \frac{1}{T-1} \sum_{t=1}^T (y_t - \bar{y})^2$ Is NOT an Unbiased Estimator of σ_y^2 If y_t Has a Trend

e: Modelling Seasonality in Time Series

- **Seasonality** can be used to model monthly housing starts (higher in June than in January), retail sales (higher in fourth quarter than in the previous three quarters because of Christmas), etc..
- A simple method is to include a set of seasonal dummies:

$$y_t = \beta_0 + \delta_1 feb_t + \delta_2 mar_t + \delta_2 apr_t + \cdots + \delta_{11} dec_t \\ + \beta_1 x_{t1} + \cdots + \beta_k x_{tk} + u_t,$$

where

$$dec_t = \begin{cases} = 1, & \text{if the observation is from december,} \\ = 0, & \text{otherwise,} \end{cases}$$

and other dummies are similarly defined.

- Similar remarks apply as in the case of deterministic time trends:
 - The regression coefficients on the explanatory variables can be seen as the result of first deseasonalizing the dependent and the explanatory variables.
 - An R -squared that is based on first **deseasonalizing** the dependent variable may better reflect the explanatory power of the explanatory variables.