## Lecture 05. Sampling Distribution Theory (Chapter 6 and Section 7.1)

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- Sampling from a Population
- Sampling Distributions of Sample Means
- Sampling Distributions of Sample Proportions
- Sampling Distributions of Sample Variances
- Properties of Point Estimators (Section 7.1)

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# Sampling from a Population

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### Population and Simple Random Sample

- Statistical analysis requires that we obtain a proper sample from a population of items of interest that have measured characteristics.
- Recall that a population means <u>all</u> (say, *N*) items of interest. If *N* is large enough, *N* can be treated as ∞. A population is generated by a process that can be modeled as a series of random experiments (see Lecture 2).
- A (simple) random sample is a sample of *n* objects drawn randomly. - Recall the definition of random sampling in Lecture 1.
- Random sampling with replacement means drawing a member from the population by chance (i.e., with probability 1/N), putting it back to the population, and then independently drawing the next one.
  - This is the random sampling in Lecture 1.
- Random sampling without replacement means randomly drawing each group of *n* distinct items with probability  $1/C_n^N$ , which seems easier in practice.
  - The first item is sampled with probability 1/N; conditional on the first item was chosen, the second item is sampled with probability 1/(N-1), etc.

### Sampling Distributions

- The randomness of a random sample comes from the random drawing, i.e., not all items are drawn (*n* < *N*) so the identities of the random sample are not determined beforehand.
- Let X be the population r.v. taking each value in  $\{x_i\}_{i=1}^N$  with probability 1/N, and  $\{x_i\}_{i=1}^n$  be a random sample.<sup>1</sup>
- The population mean  $\mu = E[X] = \frac{1}{N} \sum_{i=1}^{N} x_i$ , and the sample mean  $\bar{x} = \frac{1}{n} \sum_{i=1}^{n} x_i$  is a natural estimator of  $\mu$ .
- The population variance  $\sigma^2 = E\left[(X \mu)^2\right] = \frac{1}{N}\sum_{i=1}^N (x_i \mu)^2$ , and the sample variance  $s^2 = \frac{1}{n-1}\sum_{i=1}^n (x_i \bar{x})^2$  is a natural estimator of  $\sigma^2$ . [The reason of n-1 instead of n will be explained below]
  - The population counterpart of  $s^2$  should be  $S^2 = \frac{1}{N-1} \sum_{i=1}^{N} (x_i \mu)^2$ .
  - The sample standard deviation is  $s = \sqrt{s^2}$ .
- The sampling distribution of a statistic such as the sample mean and sample variance is the probability distribution obtained from all possible samples of the same number of observations drawn from the population.

<sup>&</sup>lt;sup>1</sup>The textbook uses  $\{X_i\}_{i=1}^n$  to emphasize the randomness of  $x_i$ , but the notations are not consistent. In my lectures, you can tell from the context whether  $\{x_i\}_{i=1}^n$  are random or just realizations. A = A + A = A

### Development of a Sampling Distribution

- Suppose a supervisor has six employees, whose years of experience are 2, 4, 6, 6, 7, 8.
- The population mean  $\mu = \frac{2+4+6+6+7+8}{6} = 5.5.$
- Two employees are randomly sampled (without replacement) to form a work group: there are  $C_2^6 = 15$  possible outcomes.

**Table 6.1** Samples and Sample Means from the Worker Population Sample Size n = 2

SAMPLE	Sample Mean	SAMPLE	SAMPLE MEAN
2,4	3.0	4,8	6.0
2,6	4.0	6,6	6.0
2,6	4.0	6,7	6.5
2,7	4.5	6, 8	7.0
2, 8	5.0	6,7	6.5
4,6	5.0	6,8	7.0
4,6	5.0	7,8	7.5
4,7	5.5		

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#### continue

**Table 6.2** Sampling Distribution of the Sample Means from the Worker Population Sample Size n = 2

Sample Mean $\overline{x}$	Probability of $\overline{x}$
3.0	1/15
4.0	2/15
4.5	1/15
5.0	3/15
5.5	1/15
6.0	2/15
6.5	2/15
7.0	2/15
7.5	1/15

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• Each of the 15 possible sample means occurs with probability 1/15, but some of them are the same so can be grouped.

#### continue

**Table 6.3** Sampling Distribution of the Sample Means from the Worker Population Sample Size n = 5

SAMPLE	$\overline{x}$	Probability
2, 4, 6, 6, 7	5.0	1/6
2, 4, 6, 6, 8	5.2	1/6
2, 4, 6, 7, 8	5.4	1/3
2, 6, 6, 7, 8	5.8	1/6
4, 6, 6, 7, 8	6.2	1/6

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• When *n* = 5, there are *C*<sub>5</sub><sup>6</sup> = 6 possible outcomes, among which two of them are the same.

#### continue



Figure: Distribution of Sample Means When n = 2 and 5

- As *n* increases, the sampling distribution becomes concentrated closer to the population mean.
- When *N* is large, it is impossible to list all possible outcomes, so the abstract analysis in the next section is helpful.

## Sampling Distributions of Sample Means

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### Mean of the Sample Means

• For random sampling with replacement,

$$\boldsymbol{E}[\bar{\boldsymbol{x}}] = \boldsymbol{E}\left[\frac{1}{n}\left(\boldsymbol{x}_1 + \cdots + \boldsymbol{x}_n\right)\right] = \frac{n\mu}{n} = \mu.$$

- In random sampling with replacement,  $x_i$  (for each *i*) and *X* have the same distribution because  $x_i$  takes each value in  $\{x_j\}_{j=1}^N$  with probability 1/N, which is exactly the distribution of *X*.

- This means that if we draw *n* samples repeatedly, and for each draw we calculate  $\bar{x}$ , then the average of these  $\bar{x}$ 's is the population mean.

- A particular  $\bar{x}$  value can be considerably far from  $\mu$ .
- Here,  $x_i$  is treated as a r.v. rather than a realization.
- (\*\*) For random sampling without replacement,

$$E[\bar{x}] = \frac{1}{n} \frac{1}{C_n^N} \sum_{j=1}^{C_n^N} \left( \sum_{i=1}^n x_i^j \right) = \frac{1}{n} \frac{1}{C_n^N} C_{n-1}^{N-1} \sum_{i=1}^N x_i = \frac{1}{N} \sum_{i=1}^N x_i = \mu,$$

where  $x_i^j$  is the *i*th draw in the *j*th sampling, and the second equality is from  $nC_n^N = NC_{n-1}^{N-1}$ .

### Variance of the Sample Means

For random sampling with replacement,

$$Var(\bar{x}) = Var\left(\frac{1}{n}x_1 + \dots + \frac{1}{n}x_n\right) = \sum_{i=1}^n \left(\frac{1}{n}\right)^2 \sigma_i^2 = \frac{n\sigma^2}{n^2} = \frac{\sigma^2}{n}$$

- Var  $(\bar{x})$  decreases with *n*, i.e., larger sample sizes result in more concentrated sampling distributions.

- Denote  $Var(\bar{x})$  as  $\sigma_{\bar{x}}^2$ ; then the standard deviation of  $\bar{x}$  is  $\sigma_{\bar{x}} = \frac{\sigma}{\sqrt{n}}$ .

• (\*) For random sampling without replacement,

$$Var(\bar{x}) = \frac{\sigma^2}{n} \cdot \frac{N-n}{N-1} = \frac{S^2}{n} \cdot \frac{N-n}{N}.$$

- Why? the variances of a hypergeometric distribution and a binomial distribution are  $np(1-p) \frac{N-n}{N-1}$  and np(1-p), respectively. The difference term  $\frac{N-n}{N-1}$  appears due to the same reason as here.

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### **Finite Population Correction Factor**

### • $\frac{N-n}{N-1}$ is often called a finite population correction factor.

- When *N* is large, the differences between the two random sampling schemes can be neglected:  $\frac{N-n}{N-1} \rightarrow 1$  as  $N \rightarrow \infty$ .

- In business applications such as auditing, *N* is indeed not large.

- *n* rather than the fraction of the sample in the population,  $\frac{n}{N}$ , is the dominant factor of  $Var(\bar{x})$ .

• Without special mention, we always mean random sampling with replacement or without replacement but *N* is large enough.

## Sampling Distribution of the Sample Means

- If the population follows the normal distribution, then  $\bar{x}$  follows a normal distribution  $N\left(\mu, \frac{\sigma^2}{n}\right)$  since it is a linear combination of  $x_i$ 's which follow the same normal distribution as the population.
  - Implicitly,  $N = \infty$  because the normal distribution is continuous.
  - Recall that a normal distribution is determined only by its mean and variance.
- The standardized normal random variable

$$z = \frac{\bar{x} - E[\bar{x}]}{\sigma_{\bar{x}}} = \frac{\bar{x} - \mu}{\sigma/\sqrt{n}} \sim N(0, 1).$$
(1)

- Terminology: the standard error (SE) of a statistic (usually an estimate of a parameter) is the standard deviation of its sampling distribution or <u>an estimate</u> of that standard deviation.
  - In our case,  $\sigma/\sqrt{n}$  and  $s/\sqrt{n}$  are both called the SE of  $\bar{x}$ .
  - Usually, only the latter is called the SE of  $\bar{x}$  because it is feasible and the former already has a name standard deviation.

### Example 6.3: Spark Plug Life

A spark plug manufacturer claims that the lives of its plugs follow N (60,000,4000<sup>2</sup>). If we observed that the sample mean of a random sample of size 16 is 58,500 miles. Do you think the manufacturer's claim is credible?
 Since

$$P(\bar{x} \le 58, 500) = P\left(\frac{\bar{x} - \mu}{\sigma/\sqrt{n}} \le \frac{58, 500 - 60, 000}{4000/\sqrt{16}}\right) = P(z \le -1.50) = .0668,$$

which is quite small, so the claim of the manufacturer is skeptical.



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Figure: (a)  $P(\bar{x} \le 58, 500)$ ; (b)  $P(z \le -1.50)$ 

## The Law of Large Numbers (LLN)

- Without normality, what is the distribution of  $\bar{x}$ ? When *n* is fixed, there is no tractable description in general, while when *n* is large, we can say something.
- First, the distribution of  $\bar{x}$  will degenerate at  $\mu$ .
- LLN: If  $x_i$ ,  $i = 1, \dots, n$ , are independent and identically distributed (i.i.d.) with mean  $\mu$  (as in a random sample with replacement), then  $\bar{x}$  approaches  $\mu$  as  $n \to \infty$ . - Not  $N \to \infty$ .
  - Only requires  $E[x_i] = \mu < \infty$ , regardless of what the distribution of  $x_i$  is.
  - This is different from  $E[\bar{x}] = \mu$  (which fixes *n* and repeatedly samples  $\{x_i\}_{i=1}^n$ ): it claims that if for **any** random sample  $\{x_i\}_{i=1}^\infty$ , we calculate  $\bar{x}$  for the first *n* samples to obtain a sequence of numbers, say  $\bar{x}_n$ , then  $\bar{x}_n \to \mu$  as  $n \to \infty$ .
  - Intuitively,  $\mu = \frac{1}{N} \sum_{i=1}^{N} x_i$  involves all values of  $\{x_i\}_{i=1}^{N}$ ; in  $E[\bar{x}] = \mu$ , although *n* is fixed, we repeatedly sampled so that all values of  $\{x_i\}_{i=1}^{n}$  would be sampled; in  $\bar{x}_n \to \mu$ , by letting  $n \to \infty$ , we potentially sampled all values  $\{x_i\}_{i=1}^{n}$ .
- (\*) Rigorously, "approach μ" means "is consistent to μ", where consistency is defined in the Appendix of Chapter 7, Page 330.
- Jacob Bernoulli proved the first LLN with  $\{x_i\}_{i=1}^n$  being Bernoulli trials (i.e.,  $x_i \stackrel{iid}{\sim}$ Bernoulli(p)); the current form of LLN is attributed to Khinchin [figure here], so is called the Khinchin LLN.

### History of the LLN



Aleksandr Khinchin (1894-1959), Moscow State University

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### The Central Limit Theorem (CLT)

- CLT: If  $x_i$ ,  $i = 1, \dots, n$ , are i.i.d. with mean  $\mu$  and variance  $\sigma^2$ , then the distribution of  $z = \frac{\bar{x} \mu}{\sigma / \sqrt{n}}$  approaches that of N(0, 1) as  $n \to \infty$ .
  - The result of CLT is stronger than that of LLN since it not only claims that  $\bar{x}$  approaches  $\mu$ , but also claims that the variance of  $\bar{x}$  approaches  $\sigma^2/n$  (which is expected), and the standardized  $\bar{x}$  is eventually bell-shaped as  $n \to \infty$  (which is surprising). That is, the distribution of  $\bar{x}$  not only degenerates at  $\mu$ , but degenerates to  $\mu$  in the rate  $\sqrt{n}$  and in the bell shape.
  - Require  $Var(x_i) = \sigma^2 < \infty$  besides  $E[x_i] = \mu < \infty$ , i.e., a stronger result need stronger assumptions.
  - It does not require x<sub>i</sub> to be normally distributed. [figure here]
  - Intuitively, when *n* is large enough, the claim for the normally distributed  $x_i$  in (1) is roughly correct, or  $\bar{x} \sim N(\mu, \sigma^2/n)$ .

- How large *n* is required for satisfactory approximation? If  $x_i$  is symmetrically distributed, then n = 20 to 25 is enough; otherwise, *n* needs to be much larger, e.g., > 50.

• The De Moivre-Laplace theorem is a special case of the CLT with  $\{x_i\}_{i=1}^n$  being Bernoulli trials; the current form of CLT is attributed to Lindeberg and Lévy [figure here], so is called the Lindeberg-Lévy CLT.

- As mentioned in the De Moivre-Laplace theorem, we can use a continuous r.v. to approximate a discrete r.v. when *n* is large.



Figure: The Sampling Distribution of  $\sqrt{n}(\bar{x} - \mu) / \sigma$  Compared with N(0, 1);  $x_i$  is discrete

Intuition:  $\sqrt{n} \rightarrow \infty$ ,  $\bar{x} - \mu \rightarrow 0$ , but  $\sqrt{n}(\bar{x} - \mu)$  will not diverge or degenerate!

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### History of the CLT



Jarl W. Lindeberg (1876-1932), University of Helsinki

Paul P. Lévy (1886-1971), École Polytechnique

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# Sampling Distributions of Sample Proportions

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## Sampling Distribution of the Sample Proportion

- Everything is the same as in the last section except that x<sub>i</sub> can only take 0 or 1 and follows the Bernoulli(p) distribution.
- Now,  $X := \sum_{i=1}^{n} x_i \sim \text{Binomial}(n, p)$ , and the sample proportion

$$\hat{p} = \frac{X}{n}$$

- $E[\hat{p}] = p$ , and  $\sigma_{\hat{p}} = \sqrt{\frac{p(1-p)}{n}}$ , where recall that  $Var(x_i) = p(1-p)$  is a function of only p its mean.
- As  $n \rightarrow \infty$ ,  $\hat{p}$  approaches p by the LLN, and

$$z = rac{\hat{p} - p}{\sigma_{\hat{p}}}$$

approaches N(0, 1) by the CLT. [figure here]

- Recall that the approximation of normality is good if  $np(1-p) > 5.^2$
- Note that  $X np = \sigma_{\hat{p}} \cdot nz = \sqrt{np(1-p)}z \sim N(0, np(1-p))$ , where

 $np(1-p) \rightarrow \infty$ , so the difference between the observed number of success and the expected number of success might increase with *n*.

<sup>2</sup>Since  $p(1-p) \leq \frac{1}{4}, n > 20.$ 



Figure: Density for  $\hat{p}$  with p = 0.80

•  $\sigma_{\hat{p}}$  decreases with *n*, and  $\hat{p}$  is approximately normally distributed.

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Sampling Distribution Theory

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### Example 6.8: Business Course Selection

- Suppose 43% of business graduates believe that a course in business ethics is very important. What is the probability of more than half of a random sample of 80 business graduates have this belief?
- Given that

$$\sigma_{\hat{p}} = \sqrt{\frac{p(1-p)}{n}} = \sqrt{\frac{0.43(1-0.43)}{80}} = 0.055,$$

we have

$$P(\hat{p} > 0.5) = P\left(\frac{\hat{p} - p}{\sigma_{\hat{p}}} > \frac{0.5 - 0.43}{0.055}\right)$$
  
=  $P(z > 1.27)$   
=  $1 - \Phi(1.27)$   
= 0.102,

where  $z \sim N(0, 1)$  by the CLT.

# Sampling Distributions of Sample Variances

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## Sampling Distribution of the Sample Variance

- Variance is important nowadays because consumers care about whether the particular item they bought works.
- Also, a smaller population variance reduces the variance of the sample mean: recall that  $\sigma_{\bar{x}}^2 = \sigma^2/n$ , where we assume random sampling with replacement or *N* is large.
- Recall that  $s^2 = \frac{1}{n-1} \sum_{i=1}^{n} (x_i \bar{x})^2$  is a natural estimator of  $\sigma^2$ .
- $E[s^2] = \sigma^2$ , and if the population r.v. *X* is <u>normally distributed</u>, then

$$lar\left(s^{2}\right)=\frac{2\sigma^{4}}{n-1},$$

and

$$\chi^2 = \frac{(n-1)s^2}{\sigma^2} = \frac{\sum_{i=1}^n (x_i - \bar{x})^2}{\sigma^2} \sim \chi^2_{n-1}$$
 [proof not required]

the chi-square distribution with (n-1) degrees of freedom (df). [see the next slide for the definition of the chi-square distribution]

Different from the CLT for the sample mean, the chi-square result is sensitive (i.e., not robust) to the normality assumption.

## $\chi^2$ -Distribution

• If  $Z_1, \dots, Z_V$  are i.i.d. such that  $Z_i \sim N(0, 1), i = 1, \dots, v$ , then

$$X = \sum_{i=1}^{\nu} Z_i^2 \sim \chi_{\nu}^2.$$



Figure: Density of the  $\chi^2_{v}$  Distribution with v = 4, 6, 8

• The  $\chi^2$  distribution can only take positive values (thinking of  $\sum_{i=1}^{v} Z_i^2 > 0$  and  $s^2 > 0$ ).

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## History of the $\chi^2$ Distribution



Friedrich R. Helmert (1843-1917), University of Berlin

• The  $\chi^2$  distribution was first described by Friedrich Robert Helmert in papers of 1875-6, and was independently rediscovered by Karl Pearson in 1900.

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## Mean and Variance of the Sample Variance

- $E \left| \chi_v^2 \right| = v$  and  $Var \left( \chi_v^2 \right) = 2v$  increase with v [refer to the figure in the last slide]. - Why? Var  $(Z_i) = E[Z_i^2] - E[Z_i]^2$  implies  $E[Z_i^2] = E[Z_i]^2 + Var(Z_i) = 0^2 + 1$ = 1, and  $Var(Z_i^2) = E[Z_i^4] - E[Z_i^2]^2 = 3 - 1^2 = 2.$ • So  $E\left[\frac{(n-1)s^2}{\sigma^2}\right] = n-1$  implies  $E\left[s^2\right] = \sigma^2$ . -  $E\left|s^{2}\right| = \sigma^{2}$  even if X is not normally distributed, i.e.,  $\frac{(n-1)s^{2}}{\sigma^{2}} \approx \chi^{2}_{n-1}$ . [(\*\*) see the next slide which follows Appendix 3 of Chapter 6, Page 287] • Also,  $Var\left(\frac{(n-1)s^2}{\sigma^2}\right) = \frac{(n-1)^2}{\sigma^4} Var\left(s^2\right) = 2(n-1)$  implies  $Var\left(s^2\right) = \frac{2(n-1)\sigma^4}{(n-1)^2}$  $=\frac{2\sigma^4}{n-1}$ , decreasing in *n* as in Var( $\bar{x}$ ). • (\*) Why lose one df in  $\sum_{i=1}^{n} (x_i - \bar{x})^2$ ? Because the *n* values  $\{(x_i - \bar{x})\}_{i=1}^{n}$  have only (n-1) "independent" or "free" values: if we know  $\{(x_i - \bar{x})\}_{i=1}^{n-1}$ , then  $(x_n - \bar{x}) = -\sum_{i=1}^{n-1} (x_i - \bar{x})$  because  $\sum_{i=1}^n (x_i - \bar{x}) = \sum_{i=1}^n x_i - \sum_{i=1}^n \bar{x} = n\bar{x} - n\bar{x} = 0.$ - The df of  $\{(x_i - \mu)\}_{i=1}^n$  is *n*, so we lose one df when we estimate  $\mu$  by  $\bar{x}$ . [see more details in the next slide]
  - In general, the number of df lost equals the number of parameters estimated.

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## (\*\*) The Mean of $s^2$ Without Normality

Note that

$$\begin{split} & \sum_{i=1}^{n} \left( x_{i} - \bar{x} \right)^{2} = \sum_{i=1}^{n} \left[ \left( x_{i} - \mu \right) - \left( \bar{x} - \mu \right) \right]^{2} \\ & = \sum_{i=1}^{n} \left[ \left( x_{i} - \mu \right)^{2} - 2 \left( \bar{x} - \mu \right) \left( x_{i} - \mu \right) + \left( \bar{x} - \mu \right)^{2} \right] \\ & = \sum_{i=1}^{n} \left( x_{i} - \mu \right)^{2} - 2 \left( \bar{x} - \mu \right) \sum_{i=1}^{n} \left( x_{i} - \mu \right) + \sum_{i=1}^{n} \left( \bar{x} - \mu \right)^{2} \\ & = \sum_{i=1}^{n} \left( x_{i} - \mu \right)^{2} - 2 n \left( \bar{x} - \mu \right)^{2} + n \left( \bar{x} - \mu \right)^{2} \\ & = \sum_{i=1}^{n} \left( x_{i} - \mu \right)^{2} - n \left( \bar{x} - \mu \right)^{2}, \end{split}$$

so

$$E\left[\sum_{i=1}^{n}\left(x_{i}-\bar{x}\right)^{2}\right]=E\left[\sum_{i=1}^{n}\left(x_{i}-\mu\right)^{2}\right]-nE\left[\left(\bar{x}-\mu\right)^{2}\right]=n\sigma^{2}-n\frac{\sigma^{2}}{n}=(n-1)\sigma^{2}.$$

- As a result,  $E\left[s^2\right] = E\left[\frac{1}{n-1}\sum_{i=1}^n (x_i \bar{x})^2\right] = \frac{1}{n-1}(n-1)\sigma^2 = \sigma^2.$
- We lose one df in  $\sum_{i=1}^{n} (x_i \bar{x})^2$  because of the extra term  $n(\bar{x} \mu)^2$  since  $\frac{\sum_{i=1}^{n} (x_i \mu)^2}{\sigma^2} = \sum_{i=1}^{n} \left(\frac{x_i \mu}{\sigma}\right)^2 = \sum_{i=1}^{n} z_i^2 \sim \chi_n^2$ , where  $z_i = \frac{x_i \mu}{\sigma}$  is the z-score of  $x_i$  and follows N(0, 1).

### Example 6.10: Process Analysis for Green Valley Foods

- The manager of Green Valley Foods wants to make sure that the variation of package weights is small. Specifically, she wants to find the upper limit of the ratio of the sample variance to the population variance for a random sample of 20 above which the probability is 0.025.
- The our target is to find  $K_{\mathcal{U}}$  such that

$$P\left(rac{s^2}{\sigma^2} > K_{U}
ight) = 0.025,$$

which implies

$$P\left(\frac{(n-1)s^2}{\sigma^2} > (n-1)K_{\mathcal{U}}\right) = P\left(\chi^2_{19} > 19K_{\mathcal{U}}\right) = 0.025,$$

SO

$$19K_{\mathscr{U}} = 32.852 \Longrightarrow K_{\mathscr{U}} = \frac{32.852}{19} = 1.729.$$

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## (\*\*) Further Results

- In random sampling without replacement,  $E\left[s^2\right] = S^2 = \frac{N}{N-1}\sigma^2$ .
- So in random sampling with replacement, an unbiased estimator of  $Var(\bar{x}) = \frac{\sigma^2}{n}$  is

$$\frac{s^2}{n}$$

and in random sampling without replacement, an unbiased estimator of  $Var(\bar{x}) = \frac{S^2}{n} \cdot \frac{N-n}{N}$  is  $\frac{s^2}{n} \cdot \frac{N-n}{N}$ ,

where unbiasedness will be defined in the next section.

• In random sampling with replacement and X is not normally distributed,

$$Var\left(s^{2}\right)=\frac{\mu_{4}}{n}-\frac{n-3}{n(n-1)}\sigma^{4},$$

which reduces to  $\frac{2\sigma^4}{n-1}$  when X is normally distributed because the fourth central moment  $\mu_4 := E\left[(X - \mu)^4\right] = 3\sigma^4$  now.<sup>3</sup>  $\frac{33\sigma^4}{n} - \frac{(n-3)\sigma^4}{n(n-1)} = \frac{3(n-1)-(n-3)}{n(n-1)}\sigma^4 = \frac{2n\sigma^4}{n(n-1)} = \frac{2\sigma^4}{n-1}$ .

### Summary

Parameter	Estimator	Mean and Var of the Est.		Dist. of Normalized Est.	
	(Normalized◊)	With Rep	Without Rep	Normality	$n \rightarrow \infty$
μ	x	$\frac{\mu}{\frac{\sigma^2}{n}}$	$\mu \over rac{\sigma^2}{n} rac{N-n}{N-1}$	-	-
	$(z = rac{ar{x} - E[ar{x}]}{\sigma_{ar{x}}})$	<del>(0,1)</del>	<del>(0,1)</del>	N(0,1)	N(0,1)†
$\sigma^2$	s <sup>2</sup>	$\frac{\sigma^2}{\frac{\mu_4}{n}-\frac{n-3}{n(n-1)}}\sigma^4\ddagger$	$S^2=rac{N}{N-1}\sigma^2$	-	-
	$(\chi^2 = \frac{(n-1)s^2}{\sigma^2})$	( <i>n</i> -1,)	$\left(\frac{N}{N-1}(n-1),?\right)$	$\chi^2_{n-1}$	?

- (◊) When studying the distributions of normalized estimators, assume x<sub>i</sub>'s are iid, i.e., randomly sampling x<sub>i</sub> with replacement.
- (†) If  $\bar{x}$  is sample proportion, i.e.,  $x_i \sim \text{Bernoulli}(p)$  (not normal), then  $E[\bar{x}] = p$ , and  $\sigma_{\bar{x}} = \sqrt{\frac{p(1-p)}{p}}$ .
- (‡) The variance reduces to  $\frac{2\sigma^4}{n-1}$  if  $x_i \sim N\left(\mu, \sigma^2\right)$ .

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## **Properties of Point Estimators**

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### Estimator and Estimate

- We mentioned "estimator" above, and here we provide a rigorous definition.
- An estimator of a population parameter is a function of the sample. If the sample is  $\{x_i\}_{i=1}^n$ , then an estimator is  $f(x_1, \dots, x_n)$  which is also a random variable given that  $x_i$  is random.
- An estimate is a <u>realized</u> value of the estimator. So an estimate is just a number.
- A point estimator of a population parameter is a function of the sample that produces a single number called a point estimate.
- An interval estimator of a population parameter is a function of the sample that produces an interval.

- An example of the interval estimator is the confidence interval that will be discussed in Lecture 7.

- No single mechanism exists for the determination of a uniquely "best" point estimator in all circumstances.
- What is available instead is a set of criteria under which particular estimators can be evaluated.
- Two criteria discussed here are unbiasedness and efficiency.

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### Unbiasedness

- A point estimator  $\hat{\theta}$  is said to be an unbiased estimator of a population parameter  $\theta$  if  $E[\hat{\theta}] = \theta$ .
- We show above that  $E[\bar{x}] = \mu$ ,  $E[\hat{p}] = p$ , and  $E[s^2] = \sigma^2$ , so  $\bar{x}, \hat{p}$  and  $s^2$  are unbiased estimators of  $\mu, p$  and  $\sigma^2$ , respectively.



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Figure: Density of an Unbiased Estimator  $\hat{\theta}_1$  and a Biased Estimator  $\hat{\theta}_2$ 

•  $\mathsf{Bias}(\hat{\theta}) = \mathsf{E}[\hat{\theta}] - \theta$ . So the bias of an unbiased estimator is 0.

### Most Efficient

- There may be many unbiased estimators. To choose among them, we use variance as a criterion.
- The unbiased estimator with the smallest variance is preferred, and is called the most efficient estimator, or the minimum variance unbiased estimator (MVUE).
- For two unbiased estimators of  $\theta$ ,  $\hat{\theta}_1$  and  $\hat{\theta}_2$ ,  $\hat{\theta}_1$  is said to be more efficient than  $\hat{\theta}_2$  if  $Var(\hat{\theta}_1) < Var(\hat{\theta}_2)$ .
- The relative efficiency of  $\hat{\theta}_1$  with respect to (w.r.t.)  $\hat{\theta}_2$  is  $Var(\hat{\theta}_2) / Var(\hat{\theta}_1)$ , i.e., if  $Var(\hat{\theta}_2) > Var(\hat{\theta}_1)$ , then  $\hat{\theta}_1$  is more efficient, so its relative efficiency w.r.t.  $\hat{\theta}_2$  is greater than 1.
- Given a random sample  $\{x_i\}_{i=1}^n$  with  $x_i \sim N(\mu, \sigma^2)$ . Both the sample mean  $\bar{x}$  and sample median  $x_{.5}$  are unbiased estimator of  $\mu$ .
- But  $Var(\bar{x}) = \frac{\sigma^2}{n}$ , and  $Var(x_{.5}) = \frac{\pi}{2} \frac{\sigma^2}{n} = \frac{1.57\sigma^2}{n}$  when *n* is large [proof not required], so the sample mean is more efficient than the sample median, and the relative efficiency of the former to the latter is

relative efficiency = 
$$\frac{Var(x_{.5})}{Var(\bar{x})} = 1.57.$$

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#### Table 7.1 Properties of Selected Point Estimators

Population Parameter	Point Estimator	Properties
Mean, μ	$\overline{X}$	Unbiased, most efficient (assuming normality)
Mean, $\mu$	Median	Unbiased (assuming normality), but not most efficient
Proportion, P	$\hat{p}$	Unbiased, most efficient
Variance, $\sigma^2$	$s^2$	Unbiased, most efficient (assuming normality)

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• (\*\*) Proof for the efficiency properties are not required.